HIGH PERFORMANCE STENCIL CODE GENERATION WITH LIFT

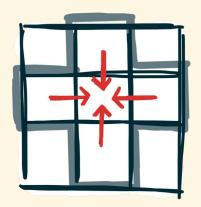
Bastian Hagedorn | Larisa Stoltzfus | Michel Steuwer | Sergei Gorlatch | Christophe Dubach







WHY STENCIL COMPUTATIONS?



Stencil computations are a class of kernels which update *neighboring* array elements according to a fixed pattern, called *stencil*.

Frequently occur in:



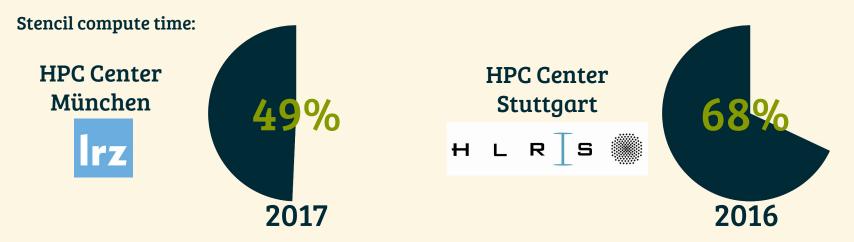


Machine Learning





WHY STENCIL COMPUTATIONS?



Frequently occur in:





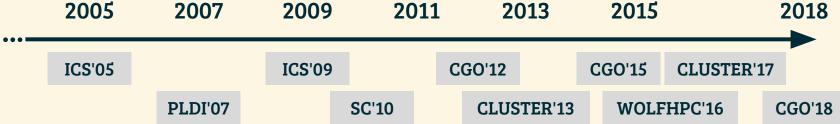
Machine Learning





YET ANOTHER STENCIL PAPER?

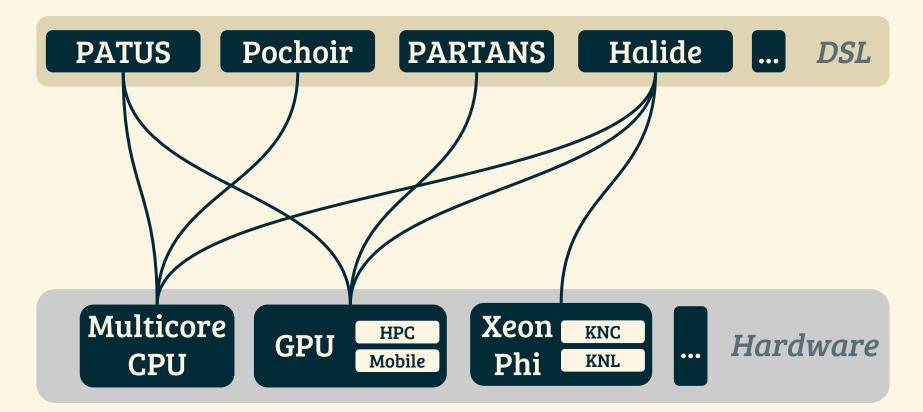




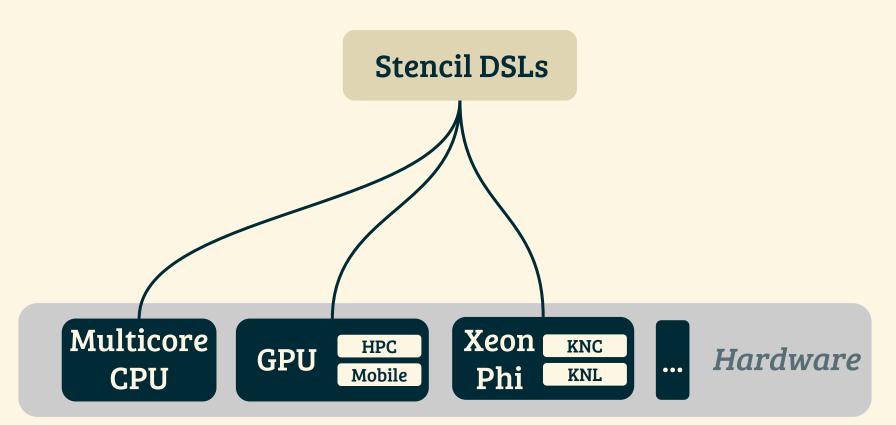
DOMAIN SPECIFIC LANGUAGES



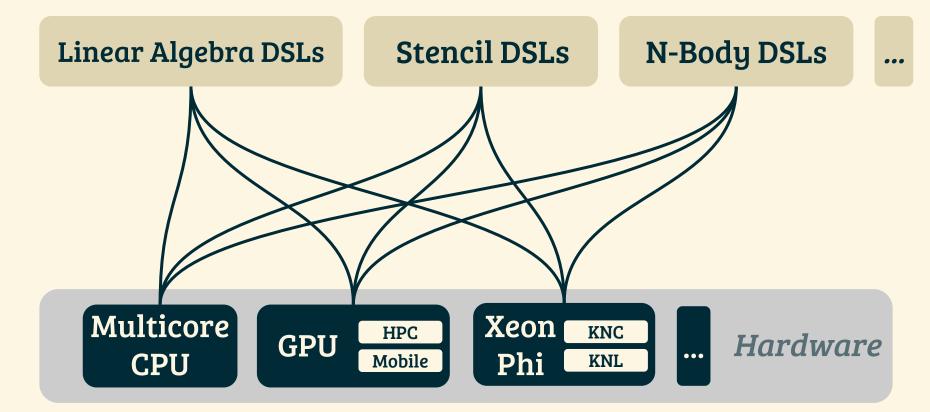
EXPLOITING DOMAIN KNOWLEDGE



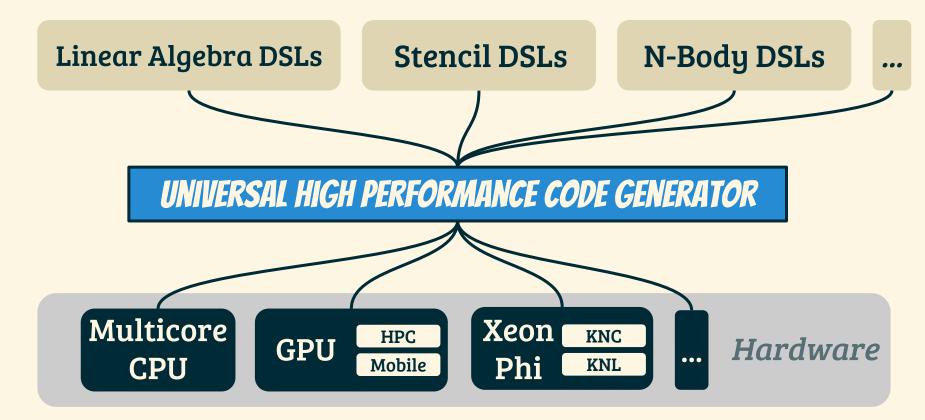
EXPLOITING DOMAIN KNOWLEDGE



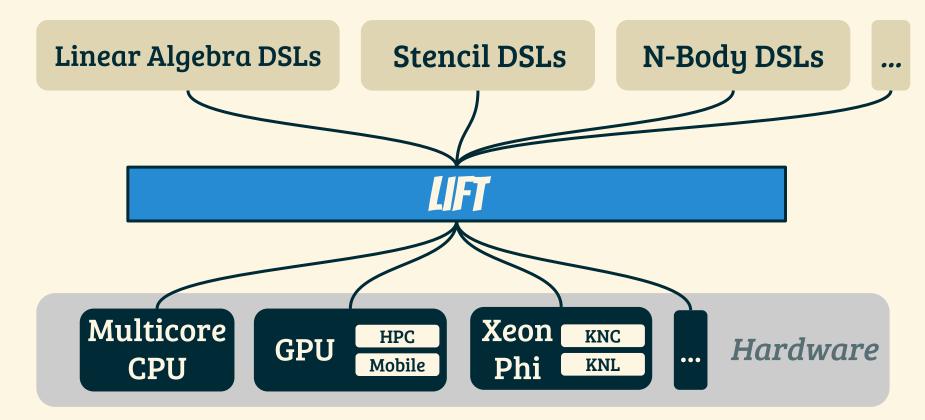
EXPLOITING DOMAIN KNOWLEDGE



APPROACHING PERFORMANCE PORTABILITY



APPROACHING PERFORMANCE PORTABILITY



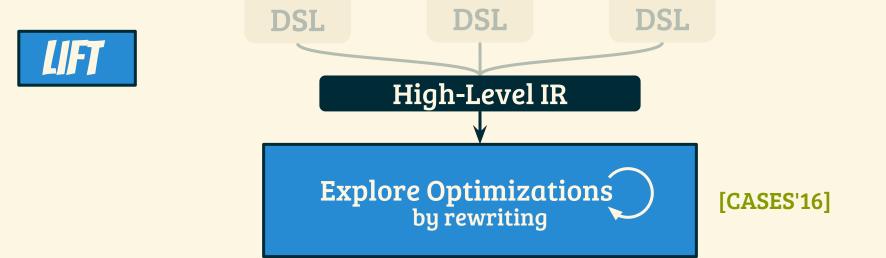




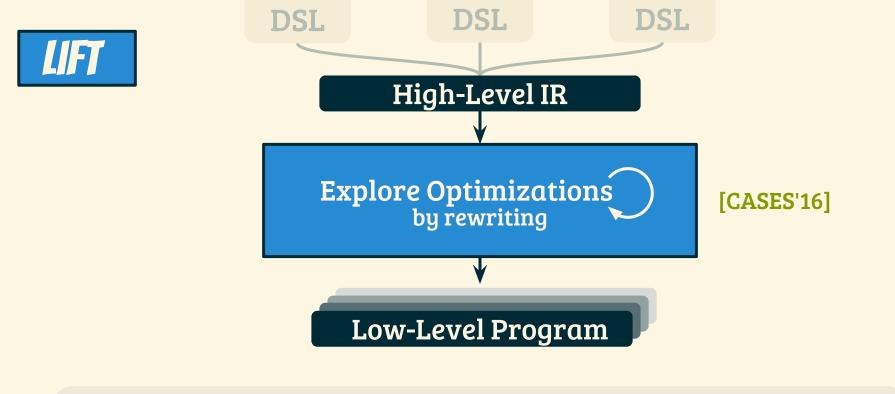




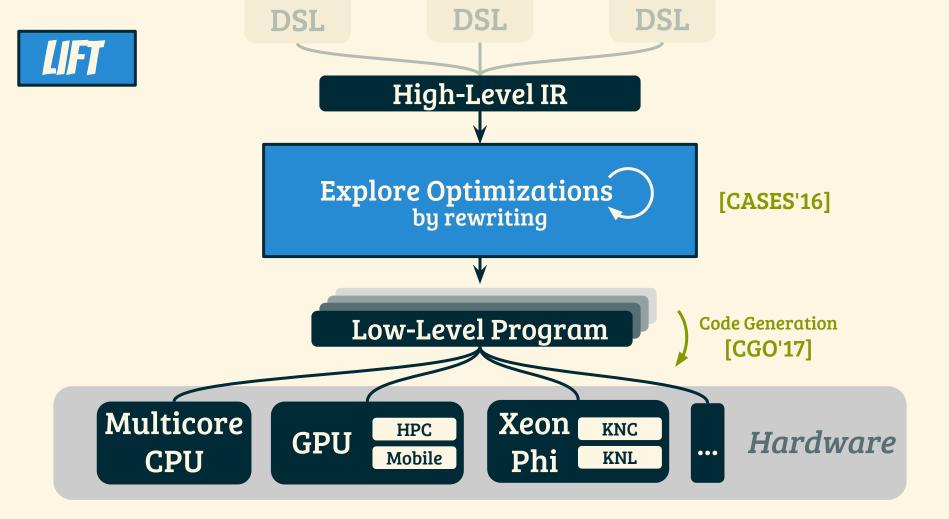


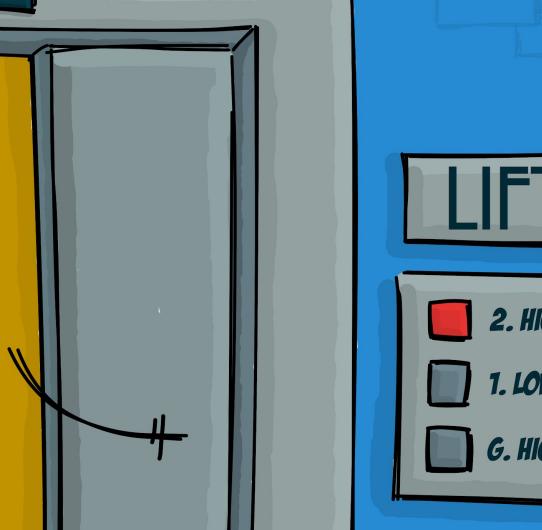




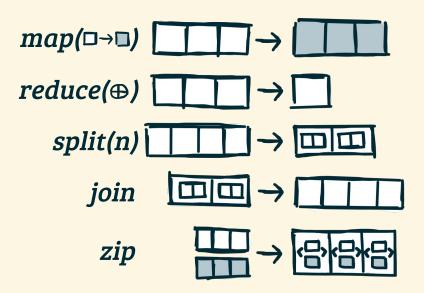


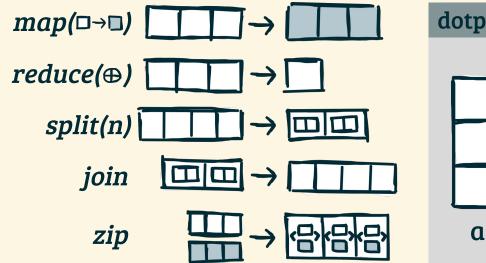






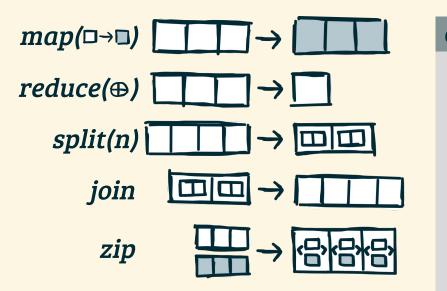
2. HIGH-LEVEL PROGRAMMING 1. LOW-LEVEL OPTIMIZATIONS G. HIGH PERFORMANCE



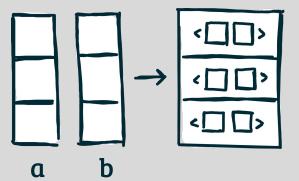


dotproduct.lift

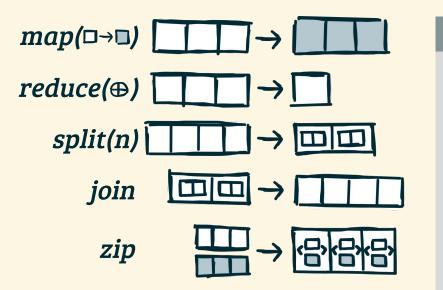
b



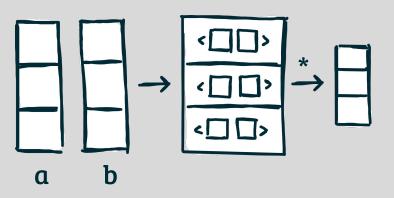
dotproduct.lift



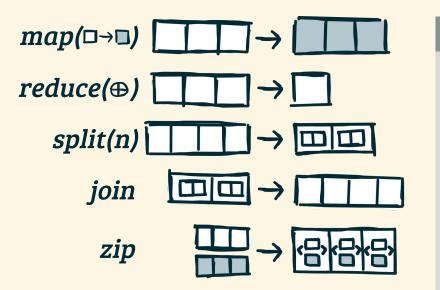
zip(a,b)



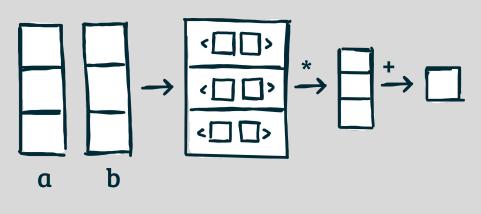
dotproduct.lift



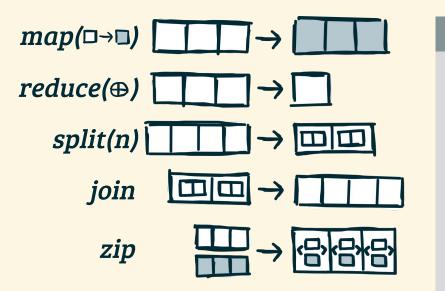
map(*, *zip*(a,b))



dotproduct.lift



reduce(+,0, *map*(*, *zip*(a,b)))



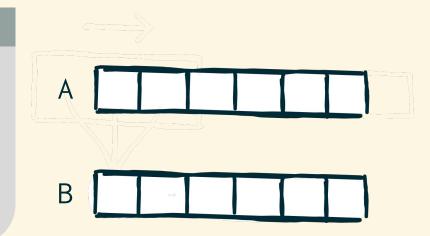
stencil.lift?

Can we express stencil computations in Lift?

Let's look at a simple stencil example...

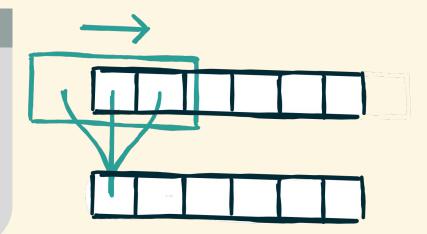
WHAT ARE STENCIL COMPUTATIONS?

```
for (int i = 0; i < N ; i ++) {
    int sum = 0;
    for ( int j = -1; j <= 1; j ++) {
        int pos = i + j;
        pos = pos < 0 ? 0 : pos;
        pos = pos > N - 1 ? N - 1 : pos;
        sum += A[ pos ]; }
B[ i ] = sum ; }
```



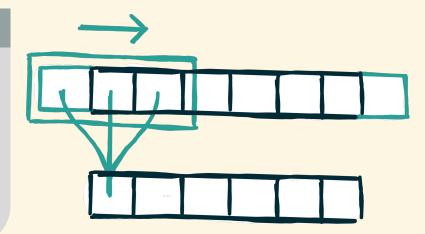
WHAT ARE STENCIL COMPUTATIONS?

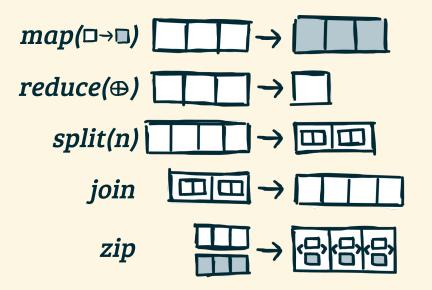
```
for (int i = 0; i < N ; i ++) {
    int sum = 0;
    for ( int j = -1; j <= 1; j ++) {
        int pos = i + j;
        pos = pos < 0 ? 0 : pos;
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        sum += A[ pos ]; }
B[ i ] = sum ; }
```



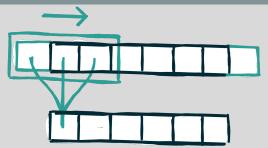
WHAT ARE STENCIL COMPUTATIONS?

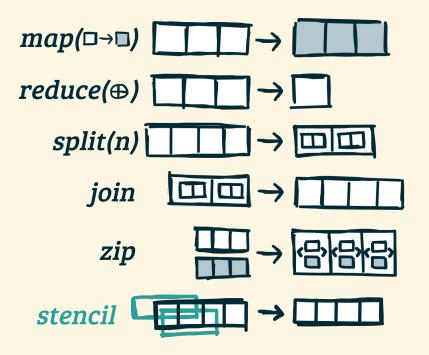
```
for (int i = 0; i < N ; i ++) {
    int sum = 0;
    for ( int j = -1; j <= 1; j ++) {
        int pos = i + j;
        pos = pos < 0 ? 0 : pos;
        pos = pos > N - 1 ? N - 1 : pos;
        sum += A[ pos ]; }
B[ i ] = sum ; }
```



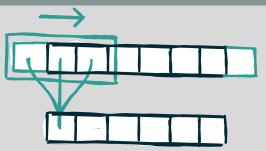


3-point-stencil.lift

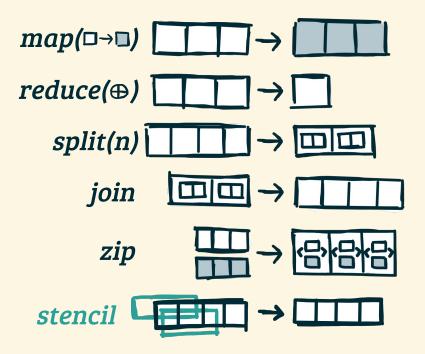




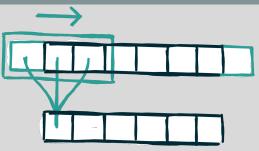
3-point-stencil.lift



Add specialized primitive: Job done?



3-point-stencil.lift



Add specialized primitive: Job done?

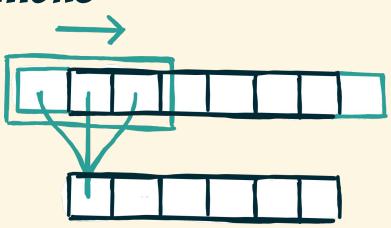
No Reuse

of existing primitives and optimizations

Domain-specific *rather than generic*

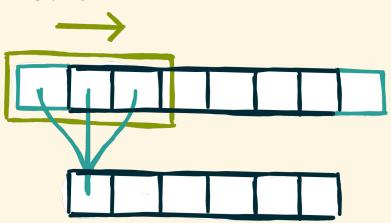
Multidimensional? *is it composable?*

```
for (int i = 0; i < N ; i ++) {
    int sum = 0;
    for ( int j = -1; j <= 1; j ++) {
        int pos = i + j;
        pos = pos < 0 ? 0 : pos;
        pos = pos > N - 1 ? N - 1 : pos;
        sum += A[ pos ]; }
B[ i ] = sum ; }
```



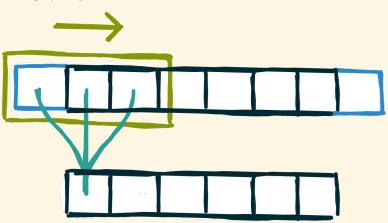
3-point-stencil.c

```
for (int i = 0; i < N ; i ++) {
    int sum = 0;
    for ( int j = -1; j <= 1; j ++) { // ( a )
        int pos = i + j;
        pos = pos < 0 ? 0 : pos;
        pos = pos > N - 1 ? N - 1 : pos;
        sum += A[ pos ]; }
B[ i ] = sum ; }
```



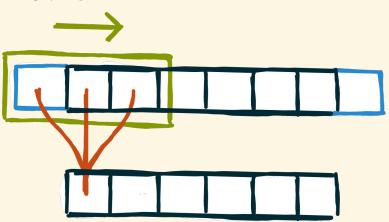
(a) access neighborhoods for every element

3-point-stencil.c



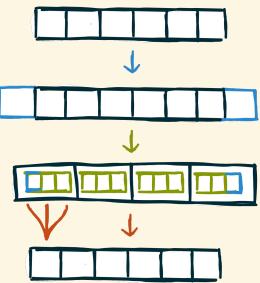
(a) access neighborhoods for every element(b) specify boundary handling

3-point-stencil.c

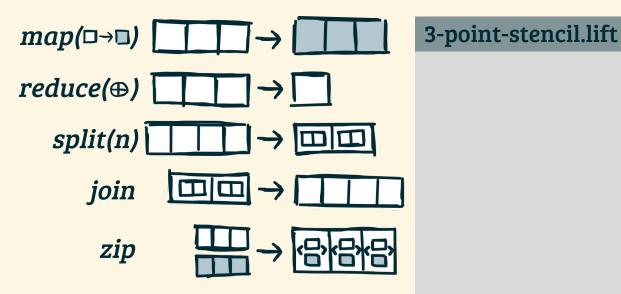


(a) access neighborhoods for every element
(b) specify boundary handling
(c) apply stencil function to neighborhoods

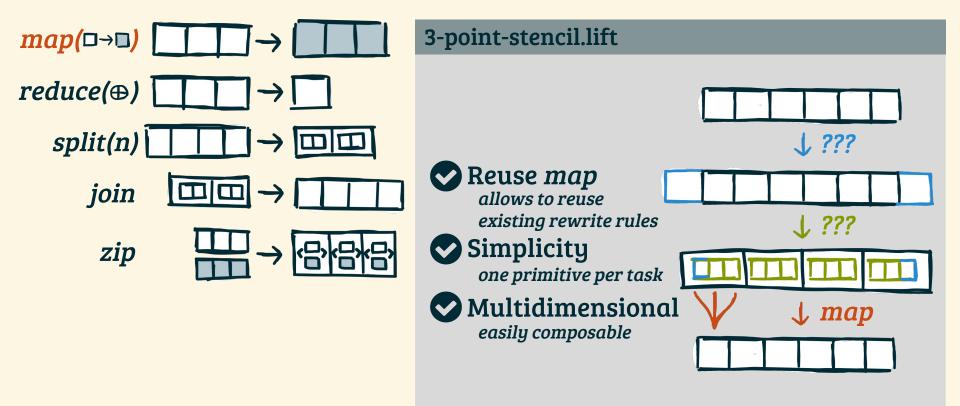
```
for (int i = 0; i < N ; i ++) {
    int sum = 0;
    for ( int j = -1; j <= 1; j ++) { // (a)
        int pos = i + j;
        pos = pos < 0 ? 0 : pos; // (b)
        pos = pos > N - 1 ? N - 1 : pos;
        sum += A[ pos ]; } // (c)
B[ i ] = sum ; }
```



- (a) access neighborhoods for every element(b) specify boundary handling
- (c) apply stencil function to neighborhoods

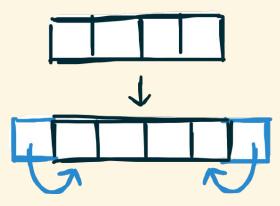


↓ ??? ↓ ??? **↓** ???

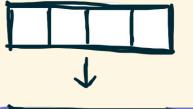


BOUNDARY HANDLING USING PAD

pad (reindexing)



pad (constant)





pad-reindexing.lift

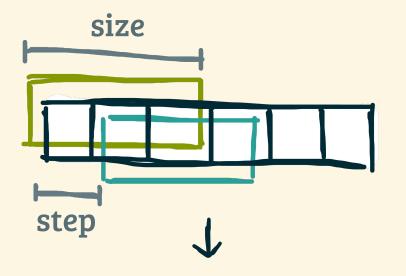
```
pad(1,1,clamp, [a,b,c,d]) =
    [a,a,b,c,d,d]
```

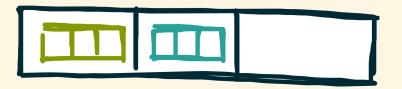
pad-constant.lift

constant(i, n) = C

pad(1,1,constant, [a,b,c,d]) =
 [C,a,b,c,d,C]

NEIGHBORHOOD CREATION USING SLIDE

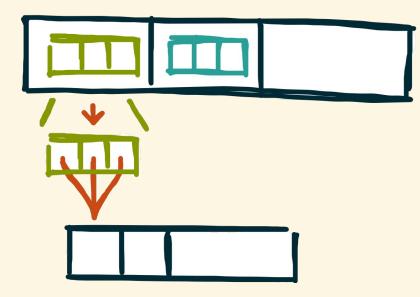




slide-example.lift

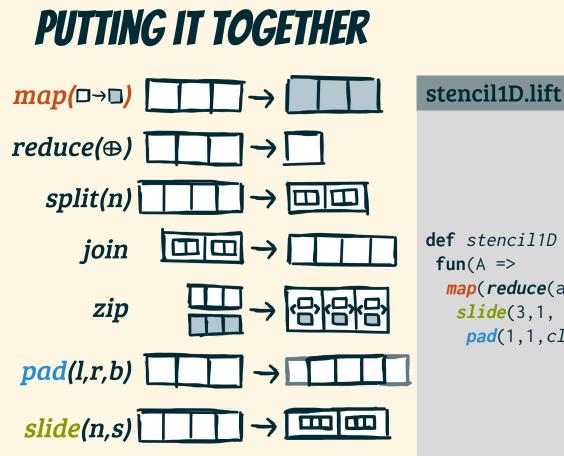
slide(3,1,[a,b,c,d,e]) = [[a,b,c],[b,c,d],[c,d,e]]

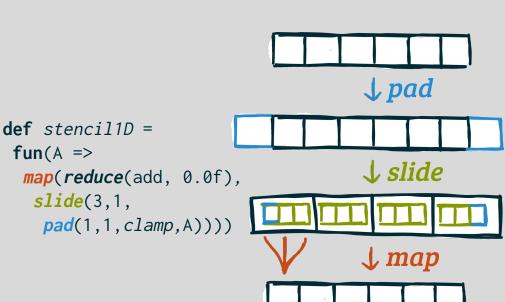
APPLYING STENCIL FUNCTION USING MAP



sum-neighborhoods.lift

map(nbh =>
 reduce(add, 0.0f, nbh))



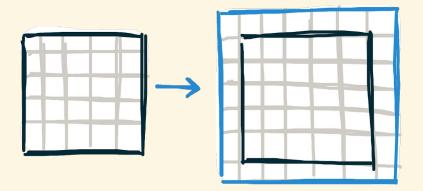


Decompose to Re Compose are expressed as compositions of intuitive, generic 1D primitives

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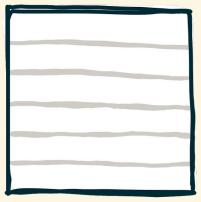
Decompose to Re Compose are expressed as compositions of intuitive, generic 1D primitives



pad_(1,1,clamp,input)

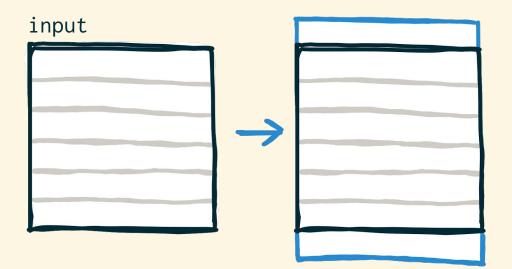
MULTIDIMENSIONAL BOUNDARY HANDLING USING PAD₂

input



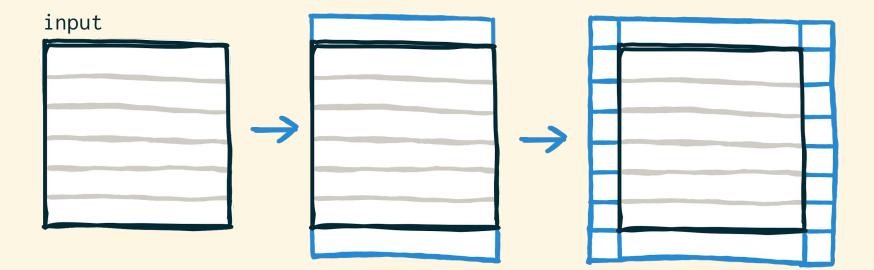


MULTIDIMENSIONAL BOUNDARY HANDLING USING PAD₂

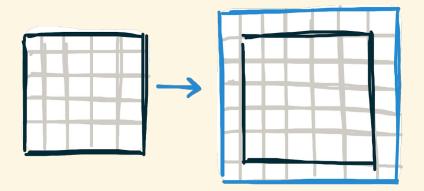


pad(1,r,b,input)

MULTIDIMENSIONAL BOUNDARY HANDLING USING PAD 2

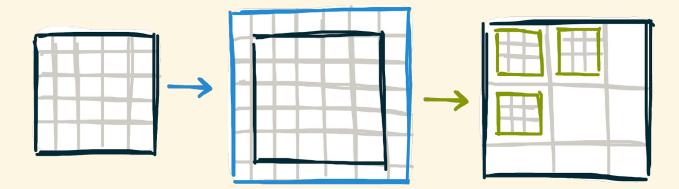


Decompose to Re Compose are expressed as compositions of intuitive, generic 1D primitives



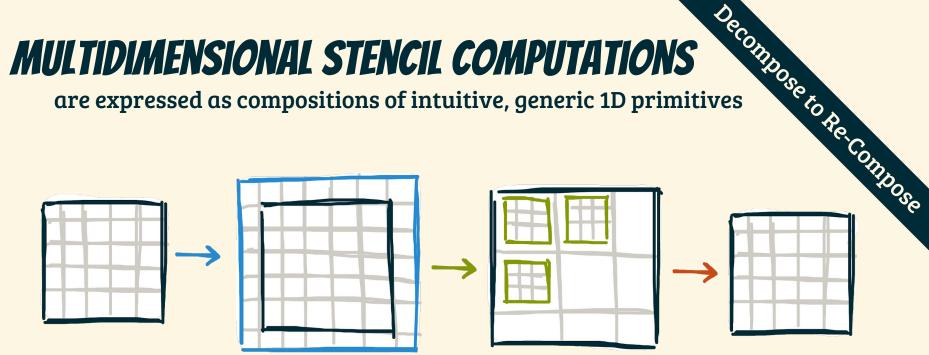
pad_(1,1,clamp,input)

Deconnoose to Re Connoose are expressed as compositions of intuitive, generic 1D primitives

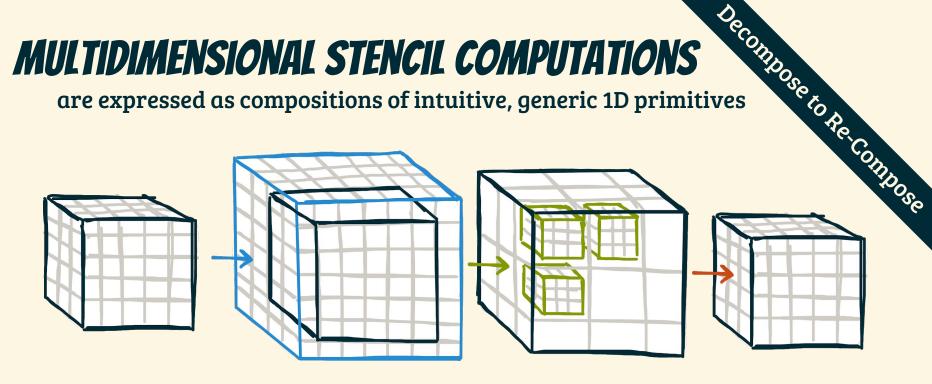


slide_(3,1, pad_(1,1,clamp,input))

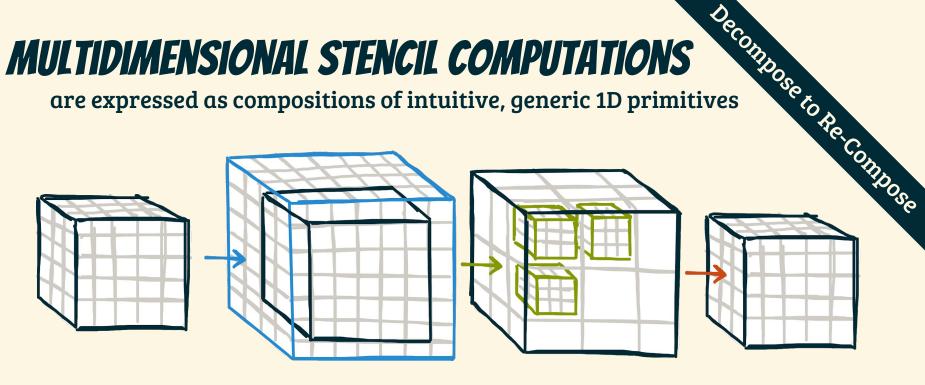
are expressed as compositions of intuitive, generic 1D primitives



map_(sum, slide_(3,1, pad_(1,1,clamp,input)))



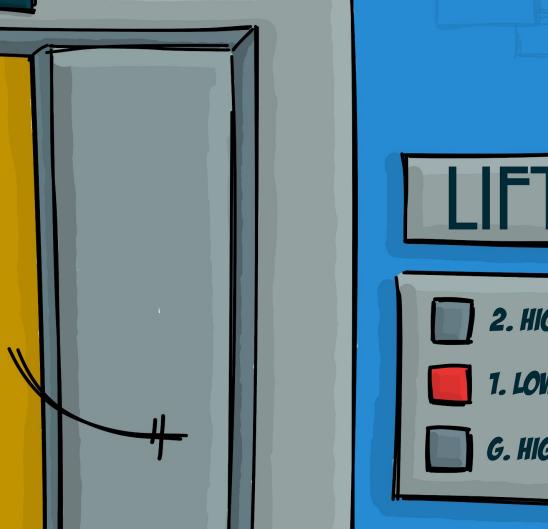
map₃(sum, slide₃(3,1, pad₃(1,1,clamp,input)))



map₃(sum, slide₃(3,1, pad₃(1,1,clamp,input)))

Advantages:



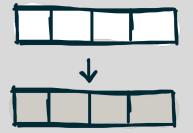


2. HIGH-LEVEL PROGRAMMING **1. LOW-LEVEL OPTIMIZATIONS** G. HIGH PERFORMANCE

REUSING EXISTING REWRITE RULES

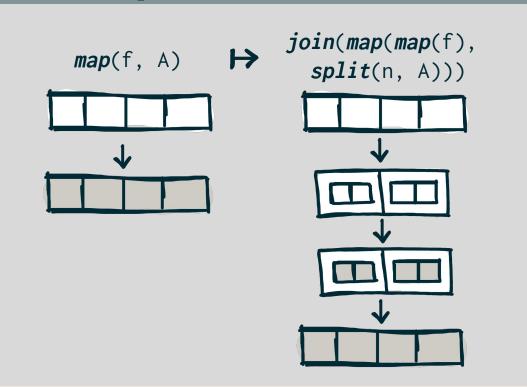
Divide & Conquer

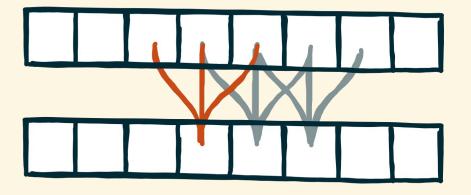
map(f, A)



REUSING EXISTING REWRITE RULES

Divide & Conquer





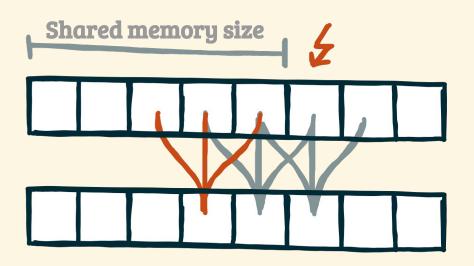


Exploit Locality

Close neighborhoods share elements that can be grouped in tiles



Shared Memory



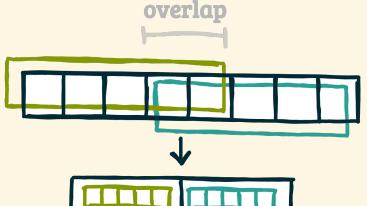


Exploit Locality

Close neighborhoods share elements that can be grouped in tiles



Shared Memory



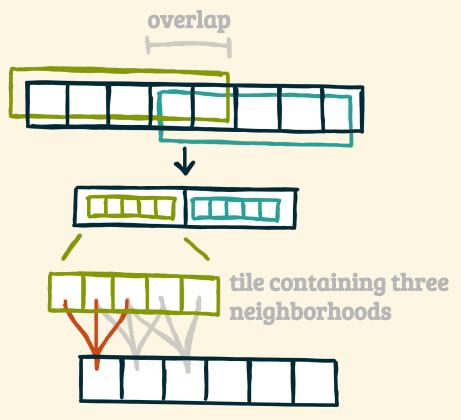


Exploit Locality

Close neighborhoods share elements that can be grouped in tiles



Shared Memory





Exploit Locality

Close neighborhoods share elements that can be grouped in tiles

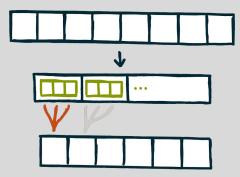


Shared Memory

OVERLAPPED TILING AS A REWRITE RULE

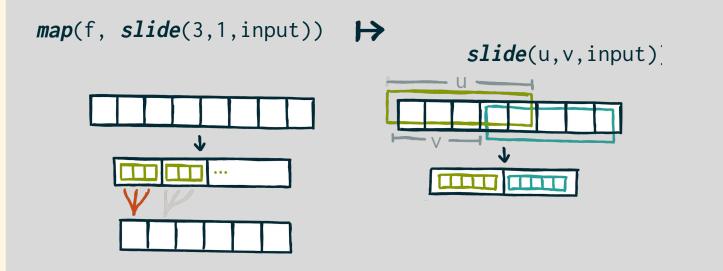
overlapped tiling rule

```
map(f, slide(3,1,input))
```



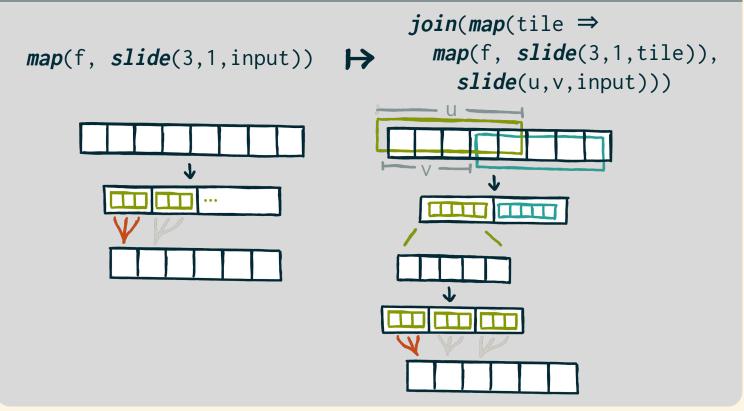
OVERLAPPED TILING AS A REWRITE RULE

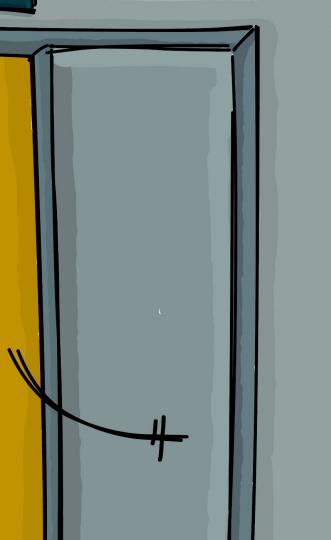
overlapped tiling rule



OVERLAPPED TILING AS A REWRITE RULE

overlapped tiling rule

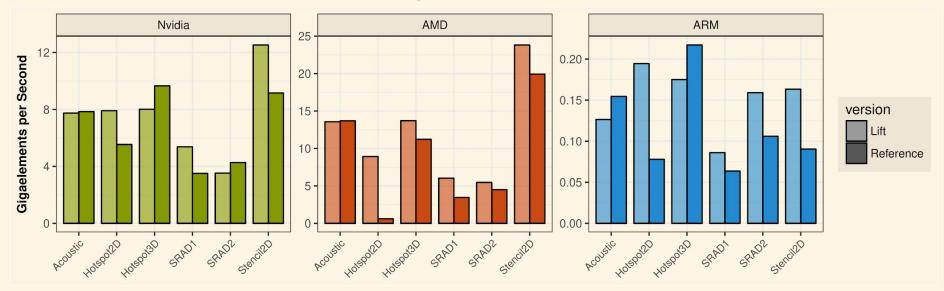






COMPARISON WITH HAND-OPTIMIZED CODES

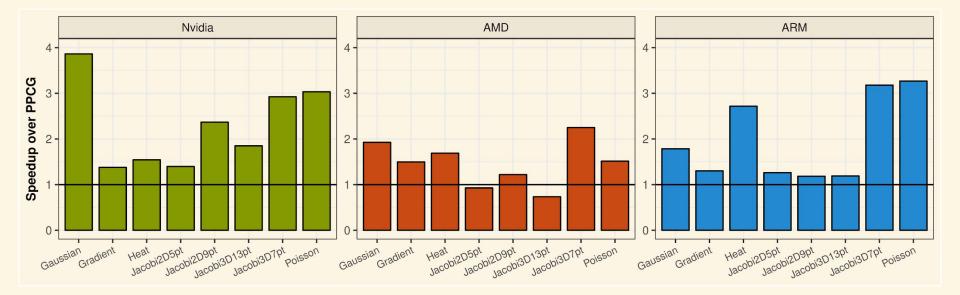
higher is better



Lift achieves the same performance as hand optimized code

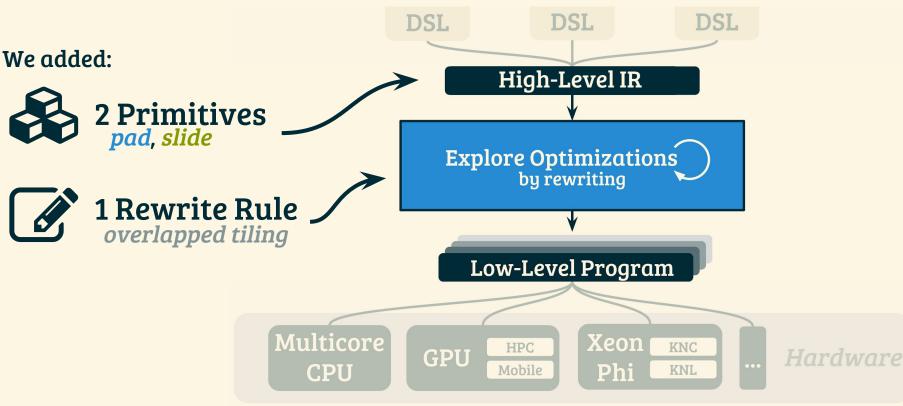
COMPARISON WITH POLYHEDRAL COMPILATION

higher is better



Lift outperforms state-of-the-art optimizing compilers

STENCIL COMPUTATIONS IN LIFT







more info at:



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